

# CSCI-351

## Data communication and Networks

### **Lecture 9: Intra Domain Routing**

# Network Layer, Control Plane

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- Function:
  - ▣ Set up routes within a single network
- Key challenges:
  - ▣ Distributing and updating routes
  - ▣ Convergence time
  - ▣ Avoiding loops

Data Plane

Application

Presentation

Session

Transport

Network

Data Link

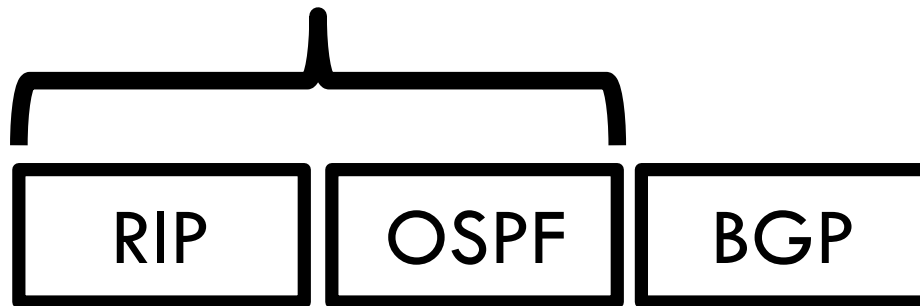
Physical

RIP

OSPF

BGP

Control Plane



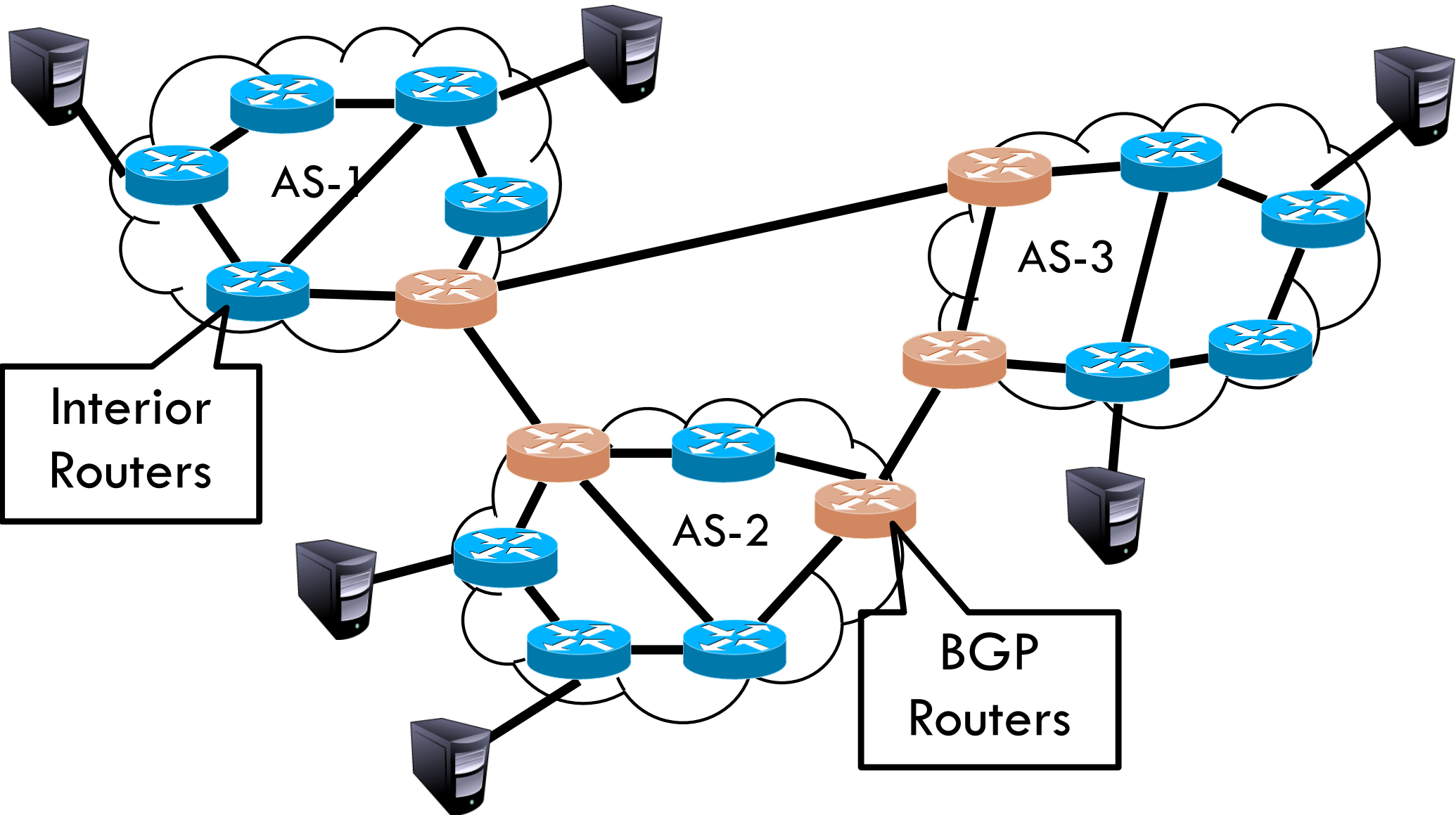
# Internet Routing

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- Internet organized as a two level hierarchy
- First level – autonomous systems (AS's)
  - ▣ AS – region of network under a single administrative domain
  - ▣ Examples: Comcast, AT&T, Verizon, Sprint, etc.
- AS's use intra-domain routing protocols internally
  - ▣ Distance Vector, e.g., Routing Information Protocol (RIP)
  - ▣ Link State, e.g., Open Shortest Path First (OSPF)
- Connections between AS's use inter-domain routing protocols
  - ▣ Border Gateway Routing (BGP)
  - ▣ De facto standard today, BGP-4

# AS Example

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# Why Do We Need ASs?

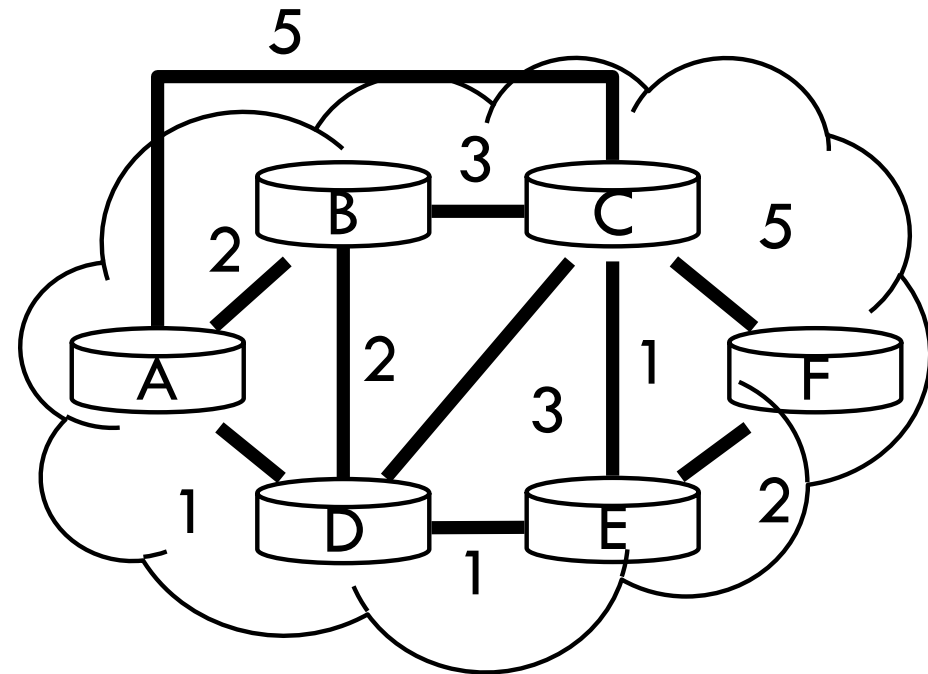
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- Routing algorithms are not efficient enough to execute on the entire Internet topology
- Different organizations may use different routing policies
- Allows organizations to hide their internal network structure
- Allows organizations to choose how to route across each other (BGP)

# Routing on a Graph (Intra –)

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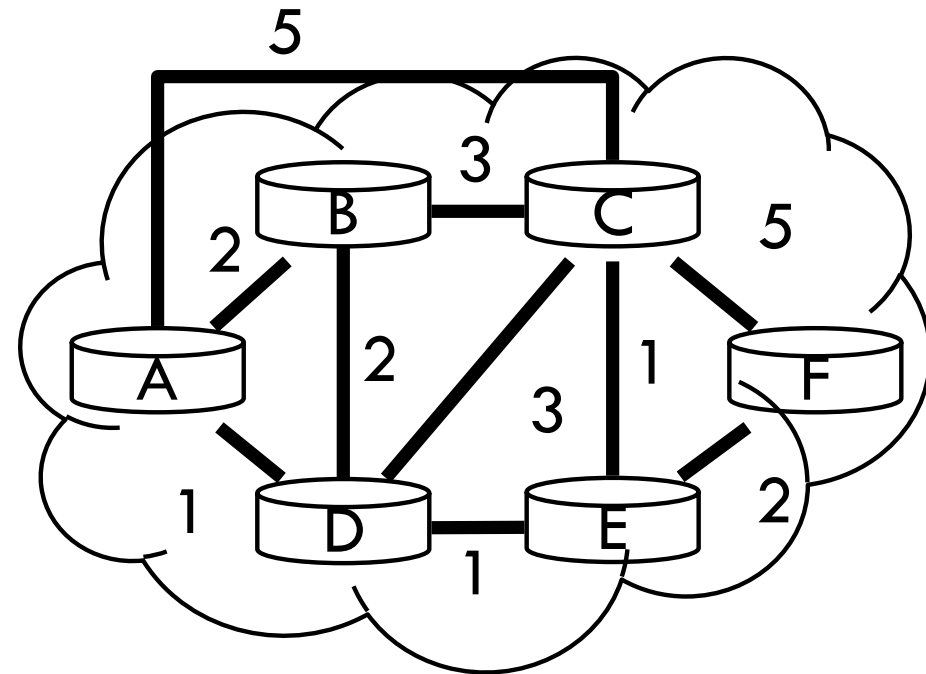
- Goal: determine a “good” path through the network from source to destination
- What is a good path?
  - ▣ Usually means the shortest path
  - ▣ Load balanced
  - ▣ Lowest \$\$\$ cost
- Network modeled as a graph
  - ▣ Routers → nodes
  - ▣ Link → edges
    - Edge cost: delay, congestion level, etc.



# Routing Problems

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- Assume
  - ▣ A network with N nodes
  - ▣ Each node only knows
    - Its immediate neighbors
    - The cost to reach each neighbor
- How does each node learn the shortest path to every other node?



# Intra-domain Routing Protocols

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- Distance vector
  - ▣ Routing Information Protocol (RIP), based on Bellman-Ford
  - ▣ Routers periodically exchange reachability information with neighbors
- Link state
  - ▣ Open Shortest Path First (OSPF), based on Dijkstra
  - ▣ Each network periodically floods immediate reachability information to all other routers
  - ▣ Per router local computation to determine full routes



# 9 Outline

## Distance Vector Routing

- RIP

## Link State Routing

- OSPF

- IS-IS (Intermediate System to Intermediate System)

# Distance Vector Routing

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- What is a distance vector?
  - ▣ Current best known cost to reach a destination
- Idea: exchange vectors among neighbors to learn about lowest cost paths

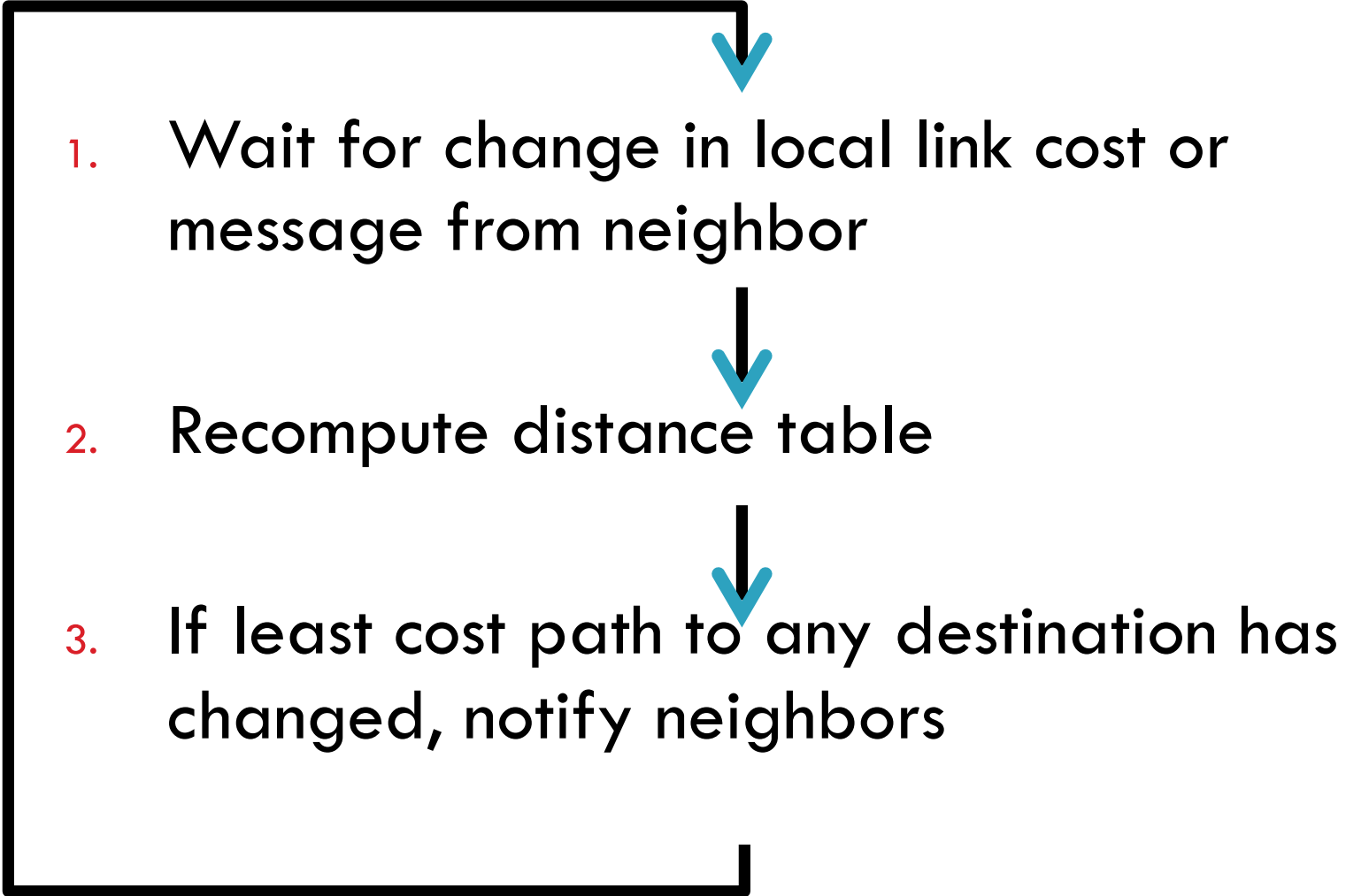
DV Table  
at Node C

Destination	Cost
A	7
B	1
D	2
E	5
F	1

- No entry for C
  - Initially, it only has info for immediate neighbors
    - ▣ Other destinations cost =  $\infty$
  - Eventually, vector is filled
- 
- Routing Information Protocol (RIP)

# Distance Vector Routing Algorithm

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- 
- ```
graph TD; A[ ] --> B[1. Wait for change in local link cost or message from neighbor]; B --> C[2. Recompute distance table]; C --> D[3. If least cost path to any destination has changed, notify neighbors]; D --> A;
```
1. Wait for change in local link cost or message from neighbor
  2. Recompute distance table
  3. If least cost path to any destination has changed, notify neighbors

# Concept of Distance Vector Algorithm

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*Bellman-Ford equation (dynamic programming)*

let

$d_x(y) :=$  cost of least-cost path from  $x$  to  $y$

then

$$d_x(y) = \min \{ c(x,v) + d_v(y) \}$$

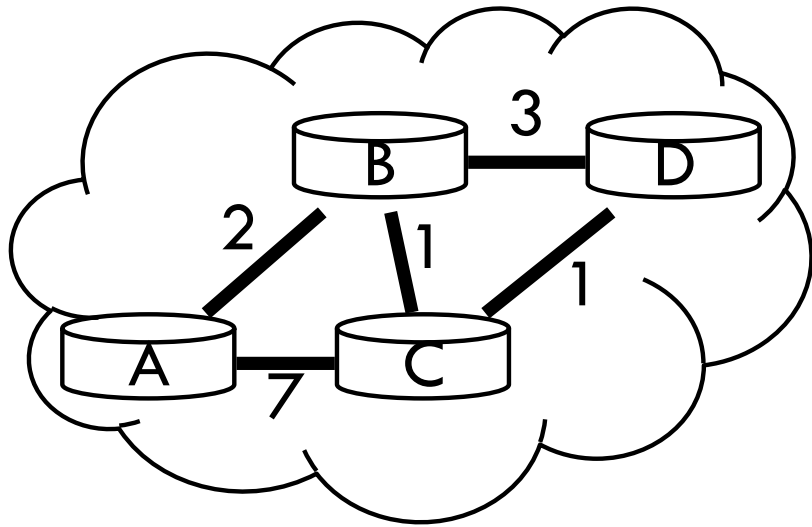
cost from neighbor  $v$  to destination  $y$

cost to neighbor  $v$

*min* taken over all neighbors  $v$  of  $x$

# Distance Vector Initialization

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Node A

| Dest. | Cost     | Next |
|-------|----------|------|
| B     | 2        | B    |
| C     | 7        | C    |
| D     | $\infty$ |      |

Node B

| Dest. | Cost | Next |
|-------|------|------|
| A     | 2    | A    |
| C     | 1    | C    |
| D     | 3    | D    |

1. Initialization:
2. for all neighbors  $V$  do
3. if  $V$  adjacent to  $A$
4.  $D(A, V) = c(A, V)$ ;
5. else
6.  $D(A, V) = \infty$ ;

...

Node C

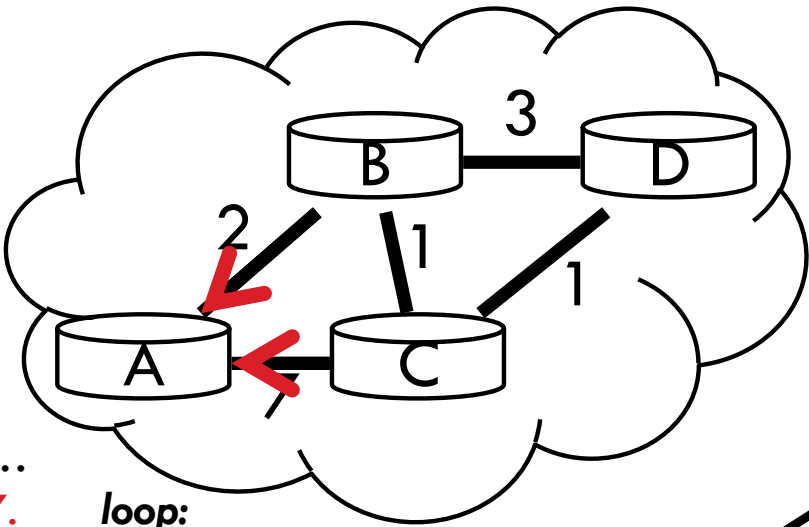
| Dest. | Cost | Next |
|-------|------|------|
| A     | 7    | A    |
| B     | 1    | B    |
| D     | 1    | D    |

Node D

| Dest. | Cost     | Next |
|-------|----------|------|
| A     | $\infty$ |      |
| B     | 3        | B    |
| C     | 1        | C    |

# Distance Vector: 1<sup>st</sup> Iteration

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Node A

| Dest. | Cost         | Next         |
|-------|--------------|--------------|
| B     | 2            | B            |
| C     | <del>3</del> | <del>C</del> |
| D     | <del>∞</del> | <del>∅</del> |

Node B

| Dest. | Cost         | Next         |
|-------|--------------|--------------|
| A     | 2            | A            |
| C     | 1            | C            |
| D     | <del>∞</del> | <del>∅</del> |

```

...
7. loop:
...
12. else if (update D(V, Y) received from V)
13.   for all destinations Y do
14.     D(A, Y) = min(D(A, Y),
15.                 D(A, V) + D(V, Y))
18.   if (there is a new min. for dest. Y)
19.     send D(A, Y) to all neighbors
20. forever
    
```

$$D(A, C) = \min(D(A, C), D(A, B) + D(B, C))$$

$$D(A, D) = \min(D(A, D), D(A, C) + D(C, D))$$

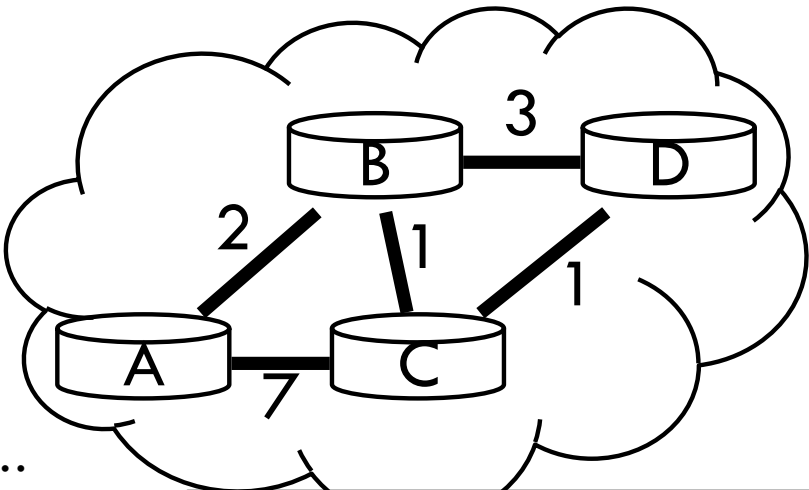
$$\equiv \min(\infty, 2 + 3) \equiv 5$$

| Dest. | Cost         | Next         |
|-------|--------------|--------------|
| A     | <del>∞</del> | <del>∅</del> |
| B     | 1            | B            |
| D     | 1            | D            |

| Dest. | Cost         | Next         |
|-------|--------------|--------------|
| A     | <del>∞</del> | <del>∅</del> |
| B     | 3            | B            |
| C     | 1            | C            |

# Distance Vector: End of 3<sup>rd</sup> Iteration

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Node A

| Dest. | Cost | Next |
|-------|------|------|
| B     | 2    | B    |
| C     | 3    | B    |
| D     | 4    | B    |

Node B

| Dest. | Cost | Next |
|-------|------|------|
| A     | 2    | A    |
| C     | 1    | C    |
| D     | 2    | C    |

...  
7.  
...  
12.  
13.  
14.  
...  
18.  
19.  
20.

```

loop
  ...
  else if (update D(V, M) received from V)
  for all destinations Y do
  D(A, Y) =
    min(D(A, Y),
        D(A, V) + D(V, Y));
  18. if (there is a new min. for dest. Y)
  19.   send D(A, Y) to all neighbors
  20. forever
  
```

Nothing changes, algorithm terminates

Until something changes

Node C

Node D

| Dest. | Cost | Next |
|-------|------|------|
| A     | 3    | B    |
| B     | 1    | B    |
| D     | 1    | D    |

| Dest. | Cost | Next |
|-------|------|------|
| A     | 4    | C    |
| B     | 2    | C    |
| C     | 1    | C    |

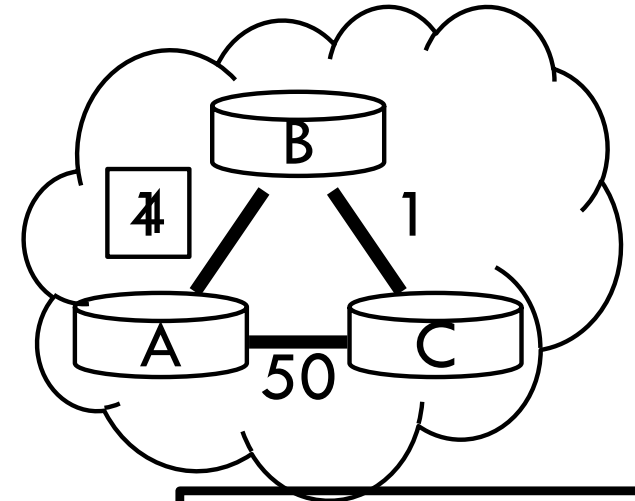


```

...
7. loop:
...
12. else if (update D(V, Y) received from V)
13.   for all destinations Y do
14.     D(A, Y) =
           min(D(A, Y),
              D(A, V) + D(V, Y));
18.   if (there is a new min. for dest. Y)
19.     send D(A, Y) to all neighbors
20. forever

```

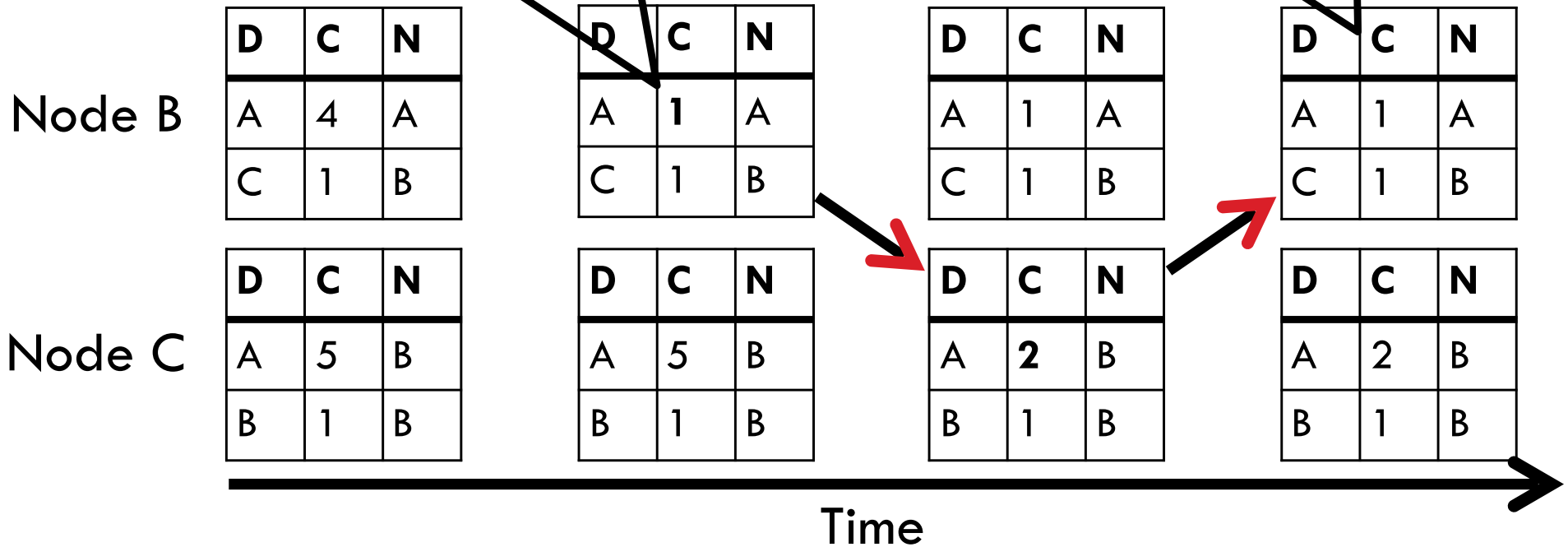
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Link Cost Changes, Algorithm Starts

Good news travels fast

Algorithm Terminates



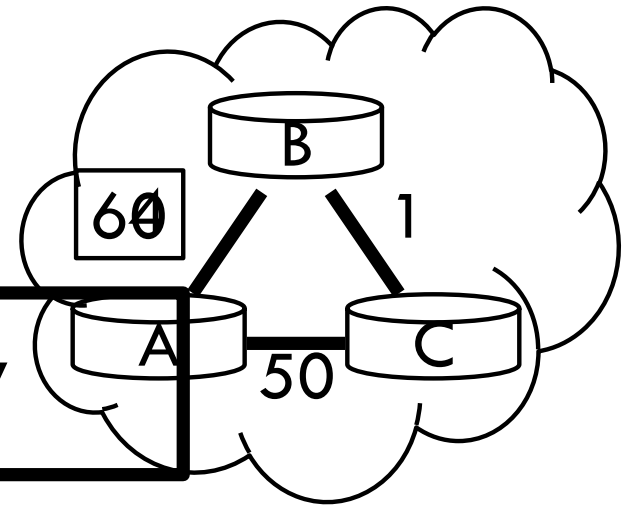


# Count to Infinity Problem

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Node B knows  $D(C, A) = 5$   
 However, B does not know the  
 path is  $C \rightarrow B \rightarrow A$

Thus,  $D(B, A)$  ~~is~~ **bad!** news travels slowly



Node B

| D | C | N |
|---|---|---|
| A | 4 | A |
| C | 1 | B |

| D | C | N |
|---|---|---|
| A | 6 | C |
| C | 1 | B |

| D | C | N |
|---|---|---|
| A | 6 | C |
| C | 1 | B |

| D | C | N |
|---|---|---|
| A | 8 | C |
| C | 1 | B |

Node C

| D | C | N |
|---|---|---|
| A | 5 | B |
| B | 1 | B |

| D | C | N |
|---|---|---|
| A | 5 | B |
| B | 1 | B |

| D | C | N |
|---|---|---|
| A | 7 | B |
| B | 1 | B |

| D | C | N |
|---|---|---|
| A | 7 | B |
| B | 1 | B |

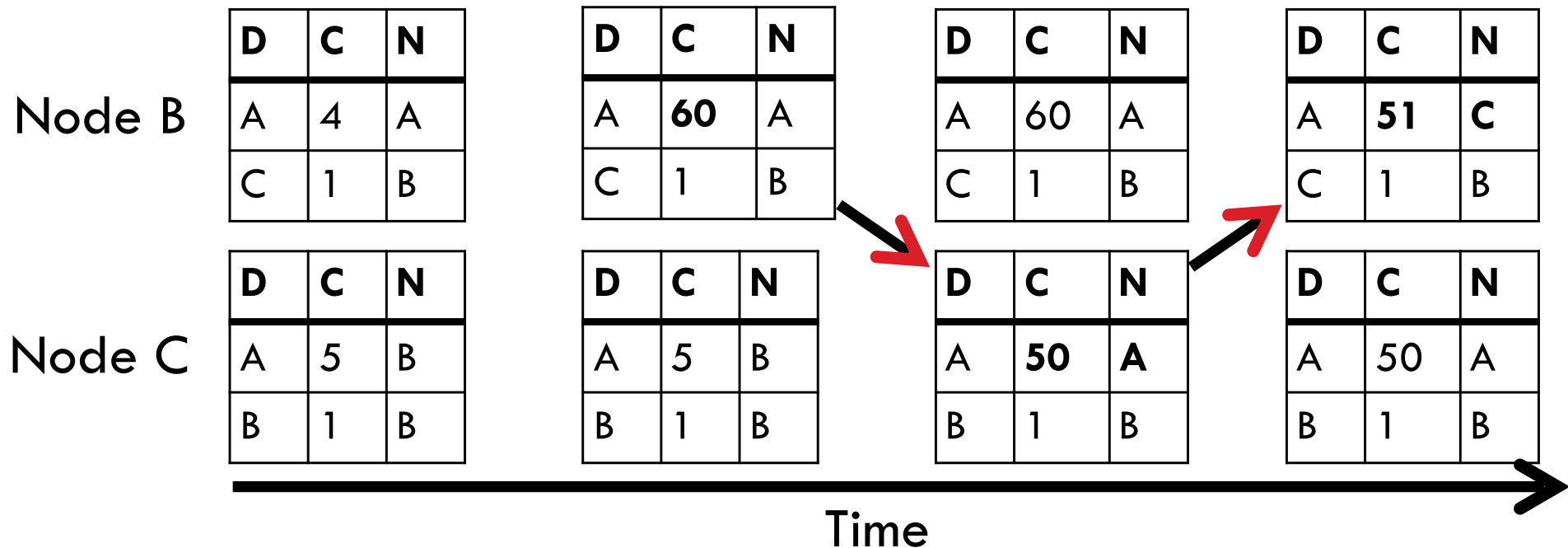
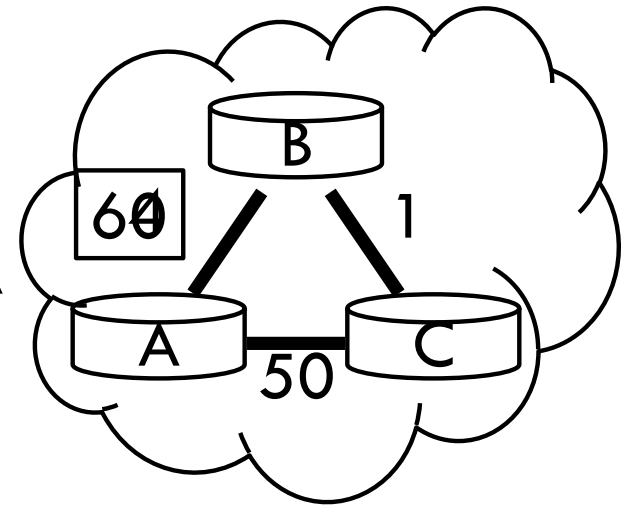
Time



# Poisoned Reverse

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- If C routes through B to get to A
  - ▣ C tells B that  $D(C, A) = \infty$ 
    - ▣ Pretending there is no direct route to A
  - ▣ Thus, B won't route to A via C



# Poisoned Reverse

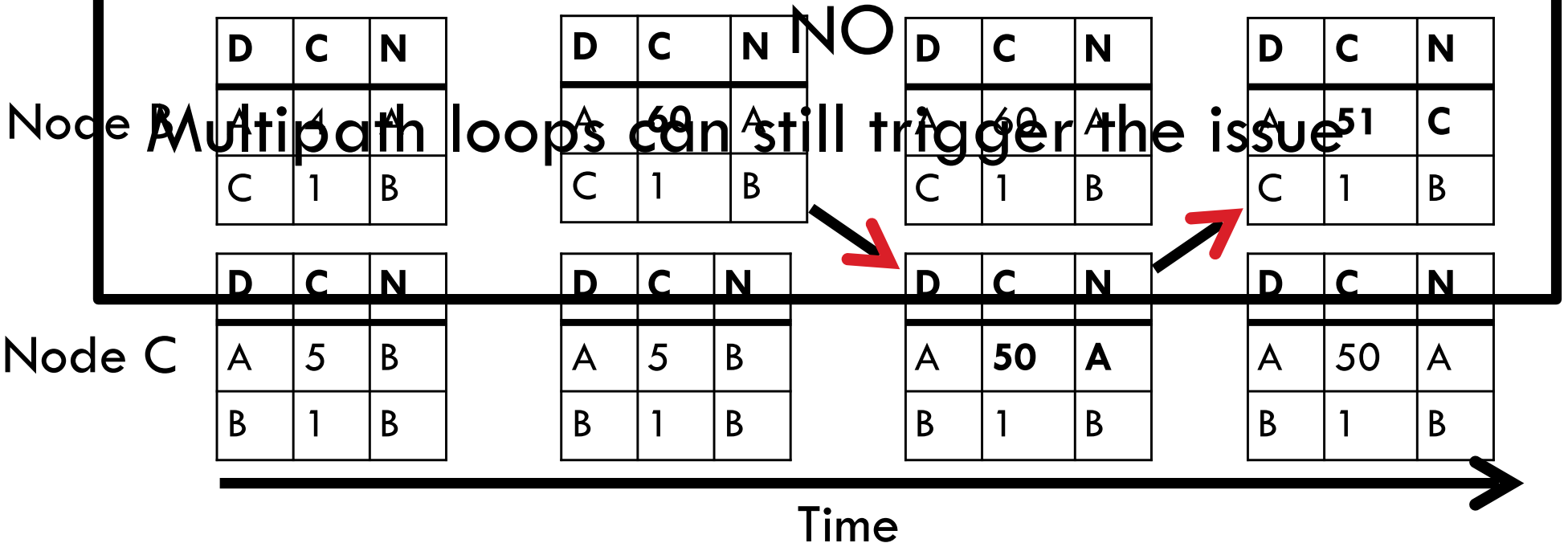
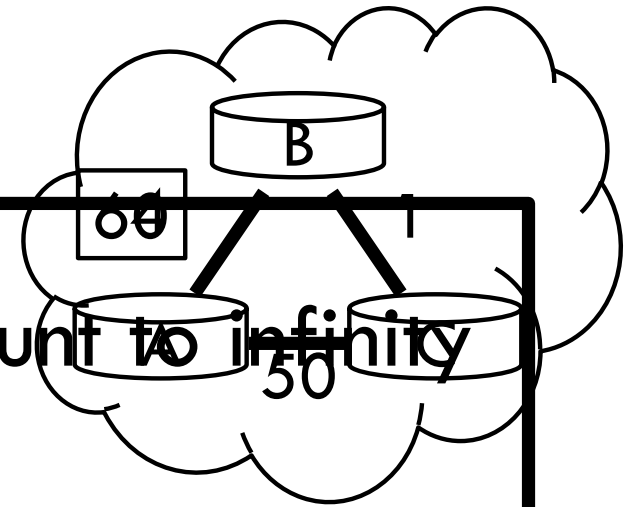
19

□ If C routes through B to get to A

□ C tells B that  $D(C, A) = \infty$

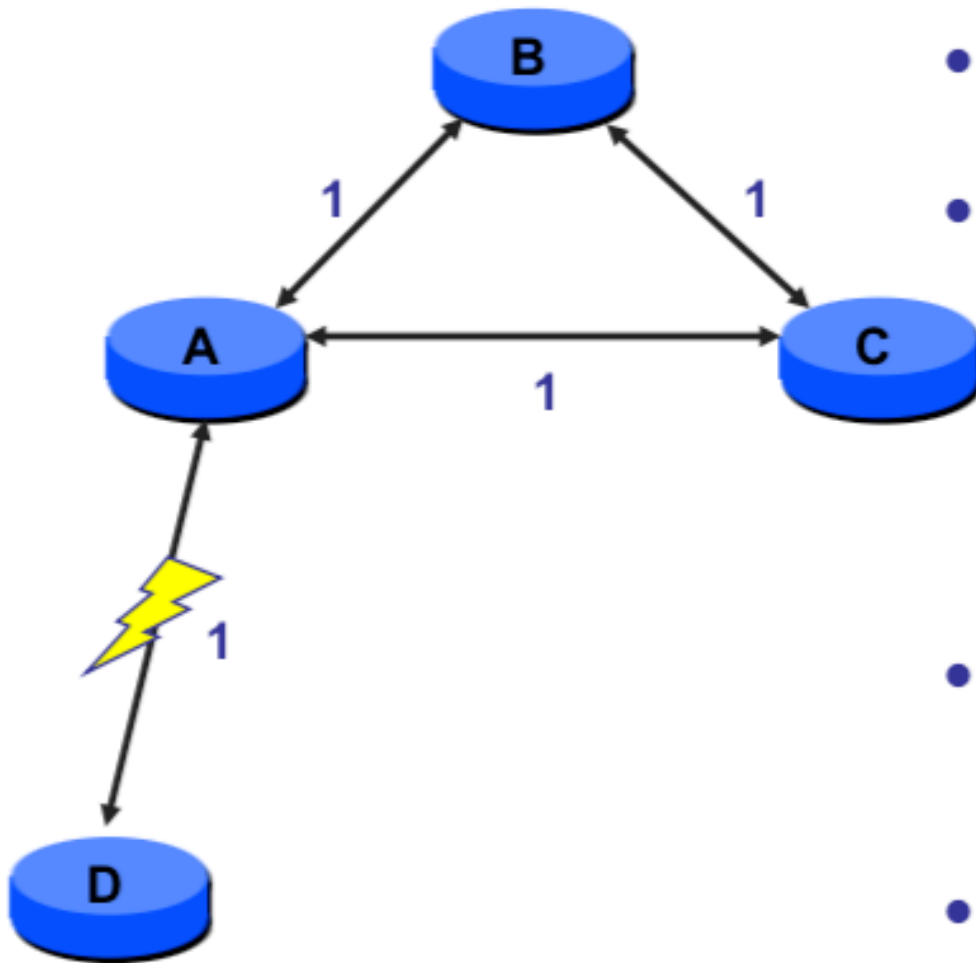
□ Thus, B won't route to A via C

Does this completely solve this count to infinity problem?



# Limitation of Poisoned Reverse

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- A tells B & C that D is unreachable
- B computes new route through C
  - Tells C that D is unreachable (poison reverse)
  - Tells A it has path of cost 3 (split horizon doesn't apply)
- A computes new route through B
  - A tells C that D is now reachable
- Etc...

# 21 Outline

## Distance Vector Routing

- RIP

## Link State Routing

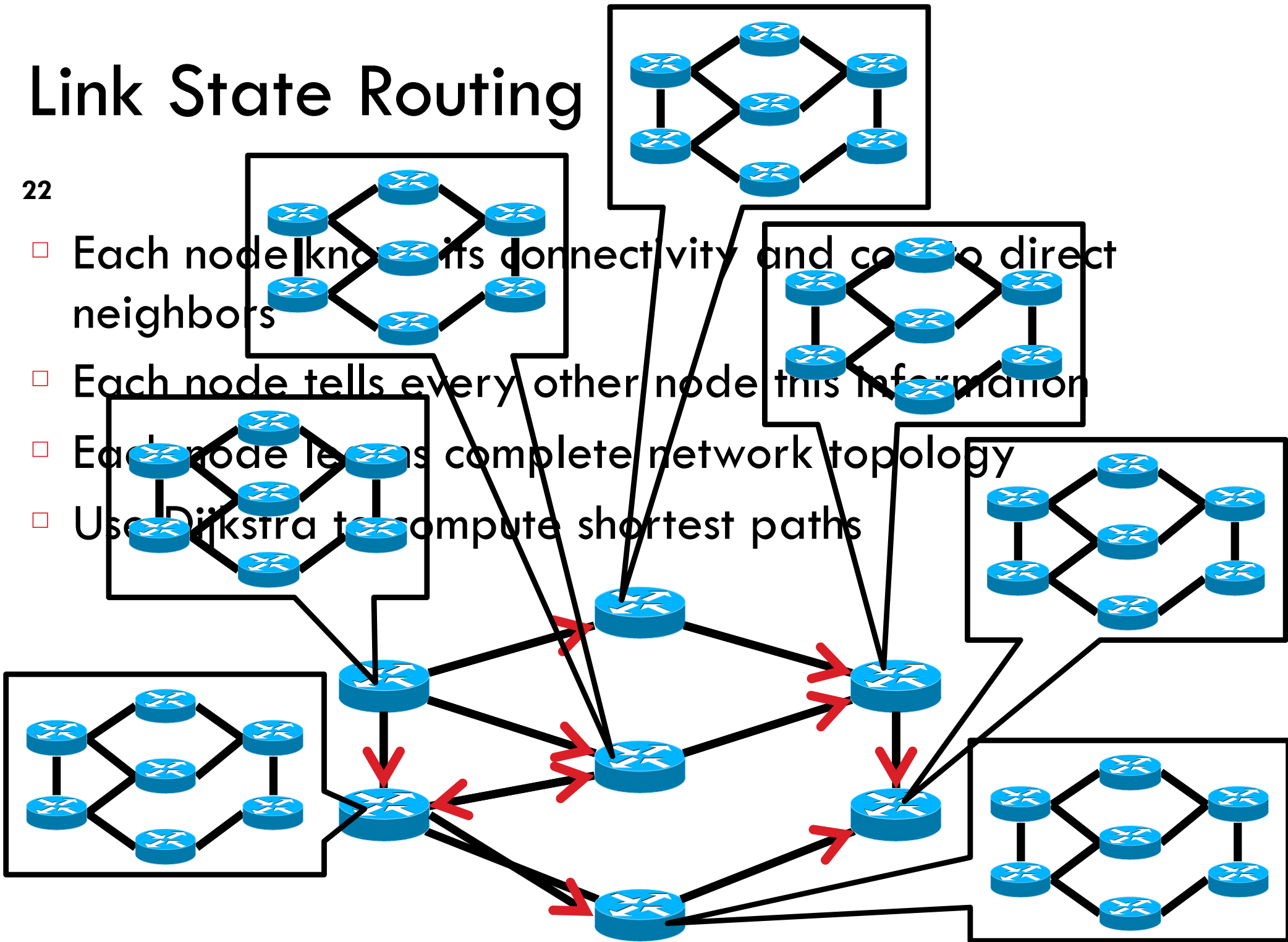
- OSPF

- IS-IS

# Link State Routing

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- Each node knows its connectivity and cost to direct neighbors
- Each node tells every other node this information
- Each node learns complete network topology
- Use Dijkstra to compute shortest paths



# Flooding Details

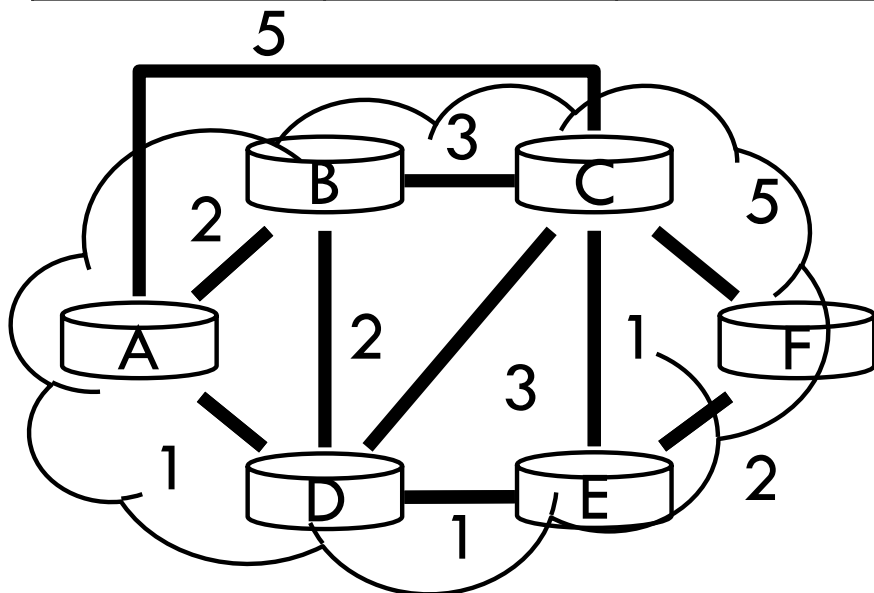
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- Each node periodically generates Link State Packet
  - ▣ ID of node generating the LSP
  - ▣ List of direct neighbors and costs
  - ▣ Sequence number (64-bit, assumed to never wrap)
  - ▣ Time to live
- Flood is reliable (ack + retransmission)
- Sequence number “versions” each LSP
- Receivers flood LSPs to their own neighbors
  - ▣ Except whoever originated the LSP
- LSPs also generated when link states change

# Dijkstra's Algorithm

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| Step | Start S | →B   | →C   | →D   | →E       | →F       |
|------|---------|------|------|------|----------|----------|
| 0    | A       | 2, A | 5, A | 1, A | $\infty$ | $\infty$ |
| 1    | AD      |      | 4, D |      | 2, D     | $\infty$ |
| 2    | ADE     |      | 3, E |      |          | 4, E     |
| 3    | ADEB    |      |      |      |          |          |
| 4    | ADEBC   |      |      |      |          |          |
| 5    | ADEBCF  |      |      |      |          |          |



...

8. **Loop 1. Initialization:**
9. find  $w \notin S$  such that  $D(w)$  is a minimum;
10. add  $w$  to  $S$ ; for all nodes  $v$
11. update  $D(v)$  if or adjacent to  $w$  and not in  $S$ :  $D(v) = c(w, v)$ ;
12.  $D(v) = \min(D(v), D(w) + c(w, v))$ ;
13. **until all nodes in  $S$ ;**



# OSPF vs. IS-IS

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- Two different implementations of link-state routing

## OSPF

- Favored by companies, datacenters
- More optional features
  
- Built on top of IPv4
  - ▣ LSAs are sent via IPv4
  - ▣ OSPFv3 needed for IPv6

## IS-IS

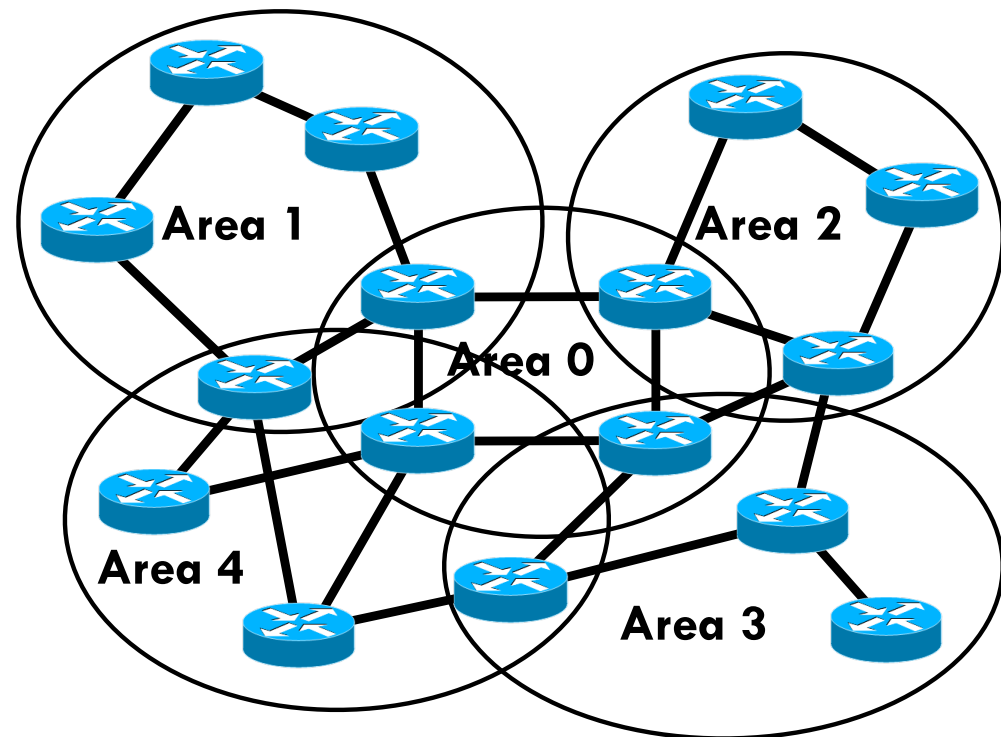
- Favored by ISPs
- Less “chatty”
  - ▣ Less network overhead
  - ▣ Supports more devices
- Not tied to IP
  - ▣ Works with IPv4 or IPv6

# Different Organizational Structure

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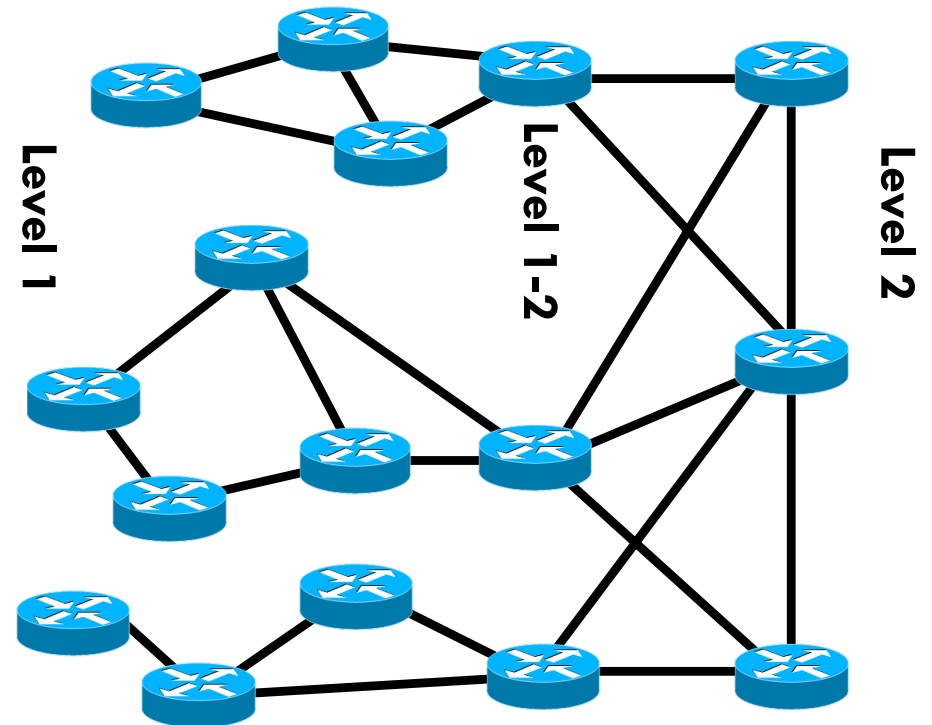
## OSPF

- Organized around overlapping areas
- Area 0 is the core network



## IS-IS

- Organized as a 2-level hierarchy
- Level 2 is the backbone



# Link State vs. Distance Vector

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|                    | Link State                                                                                                                                 | Distance Vector                                                                                                                                     |
|--------------------|--------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------|
| Message Complexity | $O(n^2 * e)$                                                                                                                               | $O(d * n * k)$                                                                                                                                      |
| Time Complexity    | $O(n * \log n)$                                                                                                                            | $O(n)$                                                                                                                                              |
| Convergence Time   | $O(1)$                                                                                                                                     | $O(k)$                                                                                                                                              |
| Robustness         | <ul style="list-style-type: none"> <li>• Nodes may advertise incorrect link costs</li> <li>• Each node computes their own table</li> </ul> | <ul style="list-style-type: none"> <li>• Nodes may advertise incorrect path cost</li> <li>• Errors propagate due to sharing of DV tables</li> </ul> |

Which is best?

$n$  = number of nodes in the graph

$d$  = degree of a given node

$k$  = number of hops

In practice, it depends.

In general, link state is more popular.